Dr. Marco Morales Aguirre Robotics

Research Topics

- Motion planning and control for autonomous robots
- Machine learning
- Computational geometry
- Computational neuroscience
- Computer architecture

Research Projects

- Machine learning for Feature-Sensitive Motion Planning
- Task and motion planning for autonomous robots
- Multi-agent motion planning

Publications

- Link to google scholar profile: Google Scholar profile

Link to CV and personal page

- <u>CV</u>
- Personal Page
- Page at ITAM

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